

James Queeney

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RESEARCH INTERESTS

I am interested in developing reliable, data-driven methods for decision making and control, with a focus on addressing barriers for real-world deployment. My current research considers the need for robustness, safety, and generalization in deep reinforcement learning.

EDUCATION

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|---|----------|
| Boston University | Aug 2023 |
| <i>PhD in Systems Engineering</i> | |
| • Dissertation: “Reliable deep reinforcement learning: Stable training and robust deployment” | |
| Boston University | Jan 2022 |
| <i>MS in Systems Engineering</i> | |
| Colgate University | May 2013 |
| <i>BA in Mathematics and Mathematical Economics</i> | |
| • Class of 2013 Valedictorian, Honors in Mathematics, Phi Beta Kappa, Summa Cum Laude | |

RESEARCH EXPERIENCE

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| Postdoctoral Research Fellow | 2023 – Present |
| <i>Mitsubishi Electric Research Laboratories</i> | |
| • Topic: Data-driven methods for decision making and control in complex applications | |
| Research Affiliate | 2023 – Present |
| <i>Massachusetts Institute of Technology – Host: Jonathan How</i> | |
| • Topic: Robust coordination and control of robotic systems | |
| Doctoral Research Fellow | 2019 – 2023 |
| <i>Boston University – Advisors: Ioannis Paschalidis, Christos Cassandras</i> | |
| • Topic: Reliable deep reinforcement learning with performance guarantees | |
| Research Intern | Summer 2022 |
| <i>Mitsubishi Electric Research Laboratories – Host: Mouhacine Benosman</i> | |
| • Publication: “Risk-averse model uncertainty for distributionally robust safe reinforcement learning” | |
| Research Assistant | 2017 – 2018 |
| <i>Colgate University – Host: William Cipolli</i> | |
| • Topic: Bayesian non-parametric approaches to supervised learning with Polya trees | |

INDUSTRY EXPERIENCE

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|---|-------------|
| Director of Operations Research | 2017 – 2018 |
| <i>Bargain Hunt</i> | |
| Private Equity Associate | 2015 – 2017 |
| <i>Thomas H. Lee Partners – Consumer & Healthcare Group</i> | |
| Investment Banking Analyst | 2013 – 2015 |
| <i>Bank of America Merrill Lynch – Mergers & Acquisitions Group</i> | |

TEACHING AND OUTREACH

CISE Graduate Student Workshop Organizer <i>Boston University Center for Information & Systems Engineering</i>	Jan 2023
Graduate Teaching Fellow <i>Boston University – Optimization Theory and Methods (SE 674)</i>	Fall 2022
Research Mentor <i>Boston University Research in Science & Engineering Program</i>	Summer 2021
Graduate Teaching Fellow <i>Boston University – Introduction to Programming for Engineers (EK 125)</i>	Fall 2019

PUBLICATIONS

Preprints

- Giammarino, V., Queeney, J., and Paschalidis, I. C. (2024). Visually robust adversarial imitation learning from videos with contrastive learning. arXiv preprint arXiv:2407.12792.
- Chen, Y., Giammarino, V., Queeney, J., and Paschalidis, I. C. (2024). Provably efficient off-policy adversarial imitation learning with convergence guarantees. arXiv preprint arXiv:2405.16668.
- Ozcan, E. C., Giammarino, V., Queeney, J., and Paschalidis, I. C. (2024). A model-based approach for improving reinforcement learning efficiency leveraging expert observations. arXiv preprint arXiv:2402.18836.
- Queeney, J., Paschalidis, I. C., and Cassandras, C. G. (2022). Generalized policy improvement algorithms with theoretically supported sample reuse. arXiv preprint arXiv:2206.13714.

Peer-Reviewed Publications

- Giammarino, V., Queeney, J., and Paschalidis, I. C. (2024). Adversarial imitation learning from visual observations using latent information. *Transactions on Machine Learning Research (TMLR)*.
- Queeney, J., Ozcan, E. C., Paschalidis, I. C., and Cassandras, C. G. (2024). Optimal transport perturbations for safe reinforcement learning with robustness guarantees. *Transactions on Machine Learning Research (TMLR)*.
- Queeney, J. and Benosman, M. (2023). Risk-averse model uncertainty for distributionally robust safe reinforcement learning. In *Advances in Neural Information Processing Systems (NeurIPS 2023)*, volume 36. Curran Associates, Inc.
- Giammarino, V., Queeney, J., Carstensen, L. C., Hasselmo, M. E., and Paschalidis, I. C. (2023). Opportunities and challenges from using animal videos in reinforcement learning for navigation. In *The 22nd World Congress of the International Federation of Automatic Control (IFAC 2023)*.
- Queeney, J., Paschalidis, I. C., and Cassandras, C. G. (2021). Generalized proximal policy optimization with sample reuse. In *Advances in Neural Information Processing Systems (NeurIPS 2021)*, volume 34. Curran Associates, Inc.
- Queeney, J., Paschalidis, I. C., and Cassandras, C. G. (2021). Uncertainty-aware policy optimization: A robust, adaptive trust region approach. In *Proceedings of the AAAI Conference on Artificial Intelligence (AAAI 2021)*, volume 35, pages 9377-9385. AAAI Press.

Dissertation

- Queeney, J. (2023). *Reliable deep reinforcement learning: Stable training and robust deployment*. PhD thesis, Boston University.

PRESENTATIONS

- Reliable deep reinforcement learning: Stable training and robust deployment (2023). *Boston University Division of Systems Engineering PhD Final Defense*, Boston, MA.
- Reliable deep reinforcement learning with robustness and safety guarantees (2023). *Mitsubishi Electric Research Laboratories Invited Talk*, Cambridge, MA.
- Safe reinforcement learning with robustness guarantees (2023). *Massachusetts Institute of Technology Invited Talk*, Cambridge, MA.
- Balancing stability and efficiency in deep reinforcement learning (2023). *Harvard University Invited Talk*, Cambridge, MA.
- Stable and efficient reinforcement learning with principled sample reuse (2022). *CISE Graduate Student Workshop 8.0*, Boston, MA. **Best Presenter Award**.
- Robust and efficient reinforcement learning from limited data (2021). *Boston University Division of Systems Engineering PhD Prospectus Defense*, Boston, MA.
- Generalized proximal policy optimization with sample reuse (2021). *35th Conference on Neural Information Processing Systems (NeurIPS 2021)*, Virtual.
- Uncertainty-aware policy optimization: A robust, adaptive trust region approach (2021). *CISE Best Student Paper Awards Presentation*, Virtual. **Best Student Paper Award Finalist**.
- Uncertainty-aware policy optimization: A robust, adaptive trust region approach (2021). *35th AAAI Conference on Artificial Intelligence (AAAI 2021)*, Virtual.

HONORS AND AWARDS

- Doctoral Research Fellow, *Boston University* 2019 – 2023
- CISE Best Student Paper Award Finalist, *Boston University* 2022
- CISE Graduate Student Workshop Best Presenter Award, *Boston University* 2022
- CISE Best Student Paper Award Finalist, *Boston University* 2021
- Dean’s Fellowship Award, *Boston University* 2018 – 2019
- Class of 2013 Valedictorian, *Colgate University* 2013
- Osborne Mathematics Prize, *Colgate University* 2013
- Phi Beta Kappa Award, *Colgate University* 2013
- Phi Beta Kappa, *Colgate University* 2013
- Summa Cum Laude, *Colgate University* 2013
- Honors in Mathematics, *Colgate University* 2013
- John T. Mitchell Award, *Colgate University* 2012 – 2013
- Charles A. Dana Scholar, *Colgate University* 2011 – 2013
- Alumni Memorial Scholar, *Colgate University* 2009 – 2013
- Sisson Mathematics Prize, *Colgate University* 2010
- Dodge Prize, *Colgate University* 2010

SKILLS

- **Programming Languages:** Python, MATLAB, R
- **Software:** DeepMind Control Suite, Gurobi, Gymnasium, Isaac Lab, MuJoCo, PyTorch, TensorFlow