

# James Queeney

Email: jim.queeney@gmail.com · Website: jqueeney.github.io

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## RESEARCH INTERESTS

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I am interested in developing reliable, data-driven methods for decision making and control, with a focus on addressing barriers for real-world deployment. My current research considers the need for robustness, safety, and generalization in deep reinforcement learning.

## EDUCATION

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|---|----------|
| <b>Boston University</b>  | Aug 2023 |
| <i>PhD in Systems Engineering</i>   |          |
| • Dissertation: “Reliable deep reinforcement learning: Stable training and robust deployment” |          |
| <b>Boston University</b>  | Jan 2022 |
| <i>MS in Systems Engineering</i>  |          |
| <b>Colgate University</b>   | May 2013 |
| <i>BA in Mathematics and Mathematical Economics</i>   |          |
| • Class of 2013 Valedictorian, Honors in Mathematics, Phi Beta Kappa, Summa Cum Laude         |          |

## RESEARCH EXPERIENCE

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| <b>Postdoctoral Research Fellow</b>  | 2023 – Present |
| <i>Mitsubishi Electric Research Laboratories</i>   |                |
| • Topic: Data-driven methods for decision making and control in complex applications                   |                |
| <b>Research Affiliate</b>  | 2023 – Present |
| <i>Massachusetts Institute of Technology – Host: Jonathan How</i>                                      |                |
| • Topic: Robust coordination and control of multi-agent systems  |                |
| <b>Doctoral Research Fellow</b>  | 2019 – 2023    |
| <i>Boston University – Advisors: Ioannis Paschalidis, Christos Cassandras</i>                          |                |
| • Topic: Reliable deep reinforcement learning with performance guarantees                              |                |
| <b>Research Intern</b>   | Summer 2022    |
| <i>Mitsubishi Electric Research Laboratories – Host: Mouhacine Benosman</i>                            |                |
| • Publication: “Risk-averse model uncertainty for distributionally robust safe reinforcement learning” |                |
| <b>Research Assistant</b>  | 2017 – 2018    |
| <i>Colgate University – Host: William Cipolli</i>  |                |
| • Topic: Bayesian non-parametric approaches to supervised learning with Polya trees                    |                |

## INDUSTRY EXPERIENCE

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| <b>Director of Operations Research</b>                                  | 2017 – 2018 |
| <i>Bargain Hunt</i>   |             |
| <b>Private Equity Associate</b>   | 2015 – 2017 |
| <i>Thomas H. Lee Partners – Consumer &amp; Healthcare Group</i>         |             |
| <b>Investment Banking Analyst</b>                                       | 2013 – 2015 |
| <i>Bank of America Merrill Lynch – Mergers &amp; Acquisitions Group</i> |             |

## TEACHING AND OUTREACH

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<b>CISE Graduate Student Workshop Organizer</b> <i>Boston University Center for Information &amp; Systems Engineering</i>	Jan 2023
<b>Graduate Teaching Fellow</b> <i>Boston University – Optimization Theory and Methods (SE 674)</i>	Fall 2022
<b>Research Mentor</b> <i>Boston University Research in Science &amp; Engineering Program</i>	Summer 2021
<b>Graduate Teaching Fellow</b> <i>Boston University – Introduction to Programming for Engineers (EK 125)</i>	Fall 2019

## PUBLICATIONS

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- Queeney, J. (2023). *Reliable deep reinforcement learning: Stable training and robust deployment*. PhD thesis, Boston University.
- Queeney, J., Ozcan, E. C., Paschalidis, I. C., and Cassandras, C. G. (2023). Optimal transport perturbations for safe reinforcement learning with robustness guarantees. arXiv preprint, arXiv:2301.13375.
- Queeney, J. and Benosman, M. (2023). Risk-averse model uncertainty for distributionally robust safe reinforcement learning. arXiv preprint, arXiv:2301.12593.
- Giammarino, V., Queeney, J., Carstensen, L. C., Hasselmo, M. E., and Paschalidis, I. C. (2023). Opportunities and challenges from using animal videos in reinforcement learning for navigation. To appear in *The 22nd World Congress of the International Federation of Automatic Control (IFAC 2023)*.
- Queeney, J., Paschalidis, I. C., and Cassandras, C. G. (2022). Generalized policy improvement algorithms with theoretically supported sample reuse. arXiv preprint, arXiv:2206.13714.
- Queeney, J., Paschalidis, I. C., and Cassandras, C. G. (2021). Generalized proximal policy optimization with sample reuse. In *Advances in Neural Information Processing Systems (NeurIPS 2021)*, volume 34. Curran Associates, Inc.
- Queeney, J., Paschalidis, I. C., and Cassandras, C. G. (2021). Uncertainty-aware policy optimization: A robust, adaptive trust region approach. In *Proceedings of the AAAI Conference on Artificial Intelligence (AAAI 2021)*, volume 35, pages 9377-9385. AAAI Press.

## PRESENTATIONS

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- Reliable deep reinforcement learning: Stable training and robust deployment (2023). *Boston University Division of Systems Engineering PhD Final Defense*, Boston, MA.
- Reliable deep reinforcement learning with robustness and safety guarantees (2023). *Mitsubishi Electric Research Laboratories Invited Talk*, Cambridge, MA.
- Safe reinforcement learning with robustness guarantees (2023). *Massachusetts Institute of Technology Invited Talk*, Cambridge, MA.
- Balancing stability and efficiency in deep reinforcement learning (2023). *Harvard University Invited Talk*, Cambridge, MA.
- Stable and efficient reinforcement learning with principled sample reuse (2022). *CISE Graduate Student Workshop 8.0*, Boston, MA. **Best Presenter Award**.
- Robust and efficient reinforcement learning from limited data (2021). *Boston University Division of Systems Engineering PhD Prospectus Defense*, Boston, MA.

- Generalized proximal policy optimization with sample reuse (2021). *35th Conference on Neural Information Processing Systems (NeurIPS 2021)*, Virtual.
- Uncertainty-aware policy optimization: A robust, adaptive trust region approach (2021). *CISE Best Student Paper Awards Presentation*, Virtual. **Best Student Paper Award Finalist.**
- Uncertainty-aware policy optimization: A robust, adaptive trust region approach (2021). *35th AAAI Conference on Artificial Intelligence (AAAI 2021)*, Virtual.

## HONORS AND AWARDS

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- Doctoral Research Fellow, *Boston University* 2019 – 2023
- CISE Best Student Paper Award Finalist, *Boston University* 2022
- CISE Graduate Student Workshop Best Presenter Award, *Boston University* 2022
- CISE Best Student Paper Award Finalist, *Boston University* 2021
- Dean’s Fellowship Award, *Boston University* 2018 – 2019
- Class of 2013 Valedictorian, *Colgate University* 2013
- Osborne Mathematics Prize, *Colgate University* 2013
- Phi Beta Kappa Award, *Colgate University* 2013
- Phi Beta Kappa, *Colgate University* 2013
- Summa Cum Laude, *Colgate University* 2013
- Honors in Mathematics, *Colgate University* 2013
- John T. Mitchell Award, *Colgate University* 2012 – 2013
- Charles A. Dana Scholar, *Colgate University* 2011 – 2013
- Alumni Memorial Scholar, *Colgate University* 2009 – 2013
- Sisson Mathematics Prize, *Colgate University* 2010
- Dodge Prize, *Colgate University* 2010

## SKILLS

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- **Programming Languages:** Python, MATLAB, R
- **Software:** DeepMind Control Suite, Gurobi, MuJoCo, OpenAI Gym, TensorFlow